# Lecture 22: Decomposition of Operators 

MATH 110-3

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July 31, 2023

## S'pose $T \in \mathcal{L}(V)$ and $\lambda \in \mathbb{F}$ :

## Def'n:

We say $v \in V$ is a generalized eigenvector if there exists positive integer $j$ such that $(T-\lambda /)^{j} v=0$.

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## Prop'n 1:

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G(\lambda, T)=\operatorname{null}(T-\lambda /)^{\operatorname{dim} V}
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## Prop'n 2:

Let $n=\operatorname{dim} V$. Then $V=\operatorname{null} T^{n} \oplus \operatorname{range} T^{n}$.

## Main Result

## Description of Operators on Complex Vector Spaces

S'pose $V$ is a complex vector space and $T \in \mathcal{L}(V)$. Let $\lambda_{1}, \ldots, \lambda_{m}$ be the distinct eigenvalues of $T$. Then

1. $V=G\left(\lambda_{1}, T\right) \oplus \cdots \oplus G\left(\lambda_{m}, T\right)$;
2. each $G\left(\lambda_{j}, T\right)$ is invariant under $T$;
3. each $\left.\left(T-\lambda_{j} I\right)\right|_{G\left(\lambda_{j}, T\right)}$ is nilpotent.

## Description of Operators on Complex Vector Spaces

## Proof.

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## Proof. Let's start with 3!

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For 2:
Lemma:
S'pose $T \in \mathcal{L}(V)$ and $p \in \mathcal{P}(\mathbb{F})$. Then null $p(T)$ and range $p(T)$ are invariant under $T$.

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How can we use to prove 2?

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Proof (cont'd).

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Hypothesis: If $\operatorname{dim} V<n$, then $V=\sum G(\lambda, T)$.

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Pick $\lambda_{1}$.

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Pick $\lambda_{1}$. How?

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Pick $\lambda_{1}$. How? Use Prop'n 2, write

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V=G\left(\lambda_{1}, T\right) \oplus \operatorname{range}\left(T-\lambda_{1} /\right)^{n}
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Call range $\left(T-\lambda_{1} I\right)^{n}=U$.

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Linear independence of $v_{j}$ guarentees $v_{j}=0$ unless possibly if $j=k$. So $v_{1}=0$ and $v=u \in U$ and $v \in G\left(\lambda_{k},\left.T\right|_{U}\right) . \square$.

## Basis of Generalized Eigenvectors

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Proof. Use previous result! $\square$.

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■ The geometric multiplicity of an eigenvalue $\lambda$ of $T$ is defined to be the dimension of the corresponding eigenspace $E(\lambda, T)$.

## Recall Example

$$
T\left(z_{1}, z_{2}, z_{3}\right)=\left(6 z_{1}+3 z_{2}+4 z_{3}, 6 z_{2}+2 z_{3}, 7 z_{3}\right)
$$

## Recall Example

$$
\begin{gathered}
T\left(z_{1}, z_{2}, z_{3}\right)=\left(6 z_{1}+3 z_{2}+4 z_{3}, 6 z_{2}+2 z_{3}, 7 z_{3}\right) \\
E(6, T)=\operatorname{span}(1,0,0) \text { and } E(7, T)=\operatorname{span}(0,0,1)
\end{gathered}
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G(6, T)=\operatorname{span}(1,0,0),(0,1,0) \text { and } G(7, T)=\operatorname{span}(10,2,1)
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G(6, T)=\operatorname{span}(1,0,0),(0,1,0) \text { and } G(7, T)=\operatorname{span}(10,2,1) \\
\mathbb{C}^{3}=G(6, T) \oplus G(7, T)
\end{gathered}
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## Sum of Multiplicities

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Proof. Use previous result! $\square$.

## Multiplicity of Eigenvalues and Upper Triangular Matrices

## Prop'n [Ax[14]:

Suppose $T \in \mathcal{L}(V)$ and $\lambda \in \mathbb{F}$. Then for every basis of $V$ with respect to which $T$ has an upper triangular matrix, the number of times that $\lambda$ appears on the diagonal of the matrix of $T$ equals the algebraic multiplicity of $\lambda$ as an eigenvalue of $T$.

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Proof: Homework challenge problem.

## Block Diagonal Matrices

Next goal: Interpret our results in matrix form.

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## Def'n:

A block diagonal matrix is a square matrix of the form

$$
\left(\begin{array}{ccc}
A_{1} & & 0 \\
& \ldots & \\
0 & & A_{m}
\end{array}\right)
$$

where $A_{1}, \ldots, A_{m}$ are square matrices lying along the diagonal and all other entries are 0.

## Example

8.28 Example The 5-by-5 matrix

$$
A=\left(\begin{array}{ccc}
\left(\begin{array}{c}
4
\end{array}\right) & 0 & 0 \\
0 \\
0 \\
0 \\
0
\end{array} \quad\left(\begin{array}{cc}
2 & -3 \\
0 & 2 \\
0 & 0 \\
0 & 0
\end{array}\right) \quad \begin{array}{ll}
0 & 0 \\
0 & 0 \\
0 & 0 \\
0 & 1
\end{array}\right) ~\left(\begin{array}{ll}
1 & 7 \\
0 &
\end{array}\right)
$$

is a block diagonal matrix with

$$
A=\left(\begin{array}{ccc}
A_{1} & & 0 \\
& A_{2} & \\
0 & & A_{3}
\end{array}\right),
$$

where

$$
A_{1}=(4), \quad A_{2}=\left(\begin{array}{cc}
2 & -3 \\
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\end{array}\right), \quad A_{3}=\left(\begin{array}{ll}
1 & 7 \\
0 & 1
\end{array}\right) .
$$

## Block Diagonal Matrix with Upper Triangular Blocks

## Prop'n:

S'pose $V$ is complex vector space and $T \in \mathcal{L}(V)$. Let $\lambda_{1}, \ldots, \lambda_{m}$ be the distinct eigenvalues of $T$, with multiplicities $d_{1}, \ldots, d_{m}$. Then there is a basis of $V$ with respect to which $T$ has a block diagonal matrix of the form

$$
\left(\begin{array}{ccc}
A_{1} & & 0 \\
& \cdots & \\
0 & & A_{m}
\end{array}\right)
$$

where each $A_{j}$ is a $d_{j} \times d_{j}$ upper triangular matrix of the form

$$
A_{j}=\left(\begin{array}{ccc}
\lambda_{j} & & * \\
& \ldots & \\
0 & & \lambda_{j}
\end{array}\right) .
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Choose a basis such that this matrix has 0's on and below the main diagonal.

## Proof of Block Diagonal UT Form

Proof. Each $\left.\left(T-\lambda_{j} /\right)\right|_{G\left(\lambda_{j}, T\right)}$ is nilpotent.
Choose a basis such that this matrix has 0's on and below the main diagonal.
What is the matrix of $\left.T\right|_{G\left(\lambda_{j}, T\right)}=\left.\left(T-\lambda_{j} /\right)\right|_{G\left(\lambda_{j}, T\right)}+\left.\lambda_{j}\right|_{G\left(\lambda_{j}, T\right)}$ ?

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Proof. Each $\left.\left(T-\lambda_{j} /\right)\right|_{G\left(\lambda_{j}, T\right)}$ is nilpotent.
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What is the matrix of $\left.T\right|_{G\left(\lambda_{j}, T\right)}=\left.\left(T-\lambda_{j} /\right)\right|_{G\left(\lambda_{j}, T\right)}+\left.\lambda_{j}\right|_{G\left(\lambda_{j}, T\right)}$ ?
The desired form.

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\end{array}\right) \quad \begin{array}{ll}
0 & 0 \\
0 & 0 \\
0 & 0
\end{array}\right)\left(\begin{array}{ll}
1 & 7 \\
0 & 1
\end{array}\right) ~ \$ ~
$$

is a block diagonal matrix with

$$
A=\left(\begin{array}{ccc}
A_{1} & & 0 \\
& A_{2} & \\
0 & & A_{3}
\end{array}\right),
$$

where

$$
A_{1}=(4), \quad A_{2}=\left(\begin{array}{cc}
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T\left(z_{1}, z_{2}, z_{3}\right)=\left(6 z_{1}+3 z_{2}+4 z_{3}, 6 z_{2}+2 z_{3}, 7 z_{3}\right)
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$$
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& =I+2 a_{1} N+\left(2 a_{2}+a_{1}^{2}\right) N^{2}+\left(2 a_{3}+2 a_{1} a_{2}\right) N^{3}+\ldots \\
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$\square$ Just solve for $a_{i}$ such that the RHS is $I+N$.

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■ Let $R_{j}$ be the root of $\lambda_{j}\left(I+\frac{N_{j}}{\lambda_{j}}\right)$.
■ Then for $v=u_{1}+\ldots+u_{m}, R v=R_{1} u_{1}+\ldots+R_{m} u_{m}$ is the square root of $T$.

## References

[Axl14] Sheldon Axter. Linear Algebra Done Right. Undergraduate Texts in Mathematics. Springer Cham, 2014.

