## Lecture 6: Linear Maps

MATH 110-3

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June 28, 2023

## Context

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"No one gets excited about vector spaces. The interesting part of linear algebra is the subject to which we now turn-linear maps."

- S. Axler


## Definition

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## Def'n:

The set of all linear maps $V$ to $W$ is denoted $\mathcal{L}(V, W)$.

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$■$ From $\mathbb{R}^{3} \rightarrow \mathbb{R}^{2}: T(x, y, z)=(2 x-y, 5 x-7 z, 2 z-y)$.
■ Generalizing from $\mathbb{F}^{n} \rightarrow \mathbb{F}^{m}$ :
Let $A_{j, k} \in \mathbb{F}$ for $j \in[m], k \in[n]$, define $T \in \mathcal{L}\left(\mathbb{F}^{n}, \mathbb{F}^{m}\right)$ as
$T\left(x_{1}, \ldots, x_{n}\right)=\left(A_{1,1} x_{1}+\ldots+A_{1, n} x_{n}, \ldots, A_{m, 1} x_{1}+\ldots+A_{m, n} x_{n}\right)$.

## Basis of Domain

## Prop'n 3.5:

Suppose $v_{1}, \ldots, v_{n}$ is a basis of $V$ and $w_{1}, \ldots, w_{n} \in W$. Then there exists a unique linear map $T: V \rightarrow W$ such that

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What does this mean?

1. I can give you any basis of $V$ and any vectors of $W$ and create a map sending basis vectors to these vectors of $W$.
2. A linear map is uniquely determined by where it sends basis vectors.

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\begin{aligned}
T(x+y) & =T\left(\left(a_{1}+b_{1}\right) v_{1}+\ldots\left(a_{n}+b_{n}\right) v_{n}\right) \\
& =\left(a_{1}+b_{1}\right) w_{1}+\ldots\left(a_{n}+b_{n}\right) w_{n} \\
& =\left(a_{1} w_{1}+\ldots a_{n} w_{n}\right)+\left(b_{1} w_{1}+\ldots b_{n} w_{n}\right) \\
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Done with existence!

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Homogeneity implies $T\left(c_{j} v_{j}\right)=c_{j} w_{j}$.
Then additivity implies $T\left(c_{1} v_{1}+\ldots+c_{n} v_{n}\right)=c_{1} w_{1}+\ldots+c_{n} w_{n}$.

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Then additivity implies $T\left(c_{1} v_{1}+\ldots+c_{n} v_{n}\right)=c_{1} w_{1}+\ldots+c_{n} W_{n}$.
Thus, $T$ must be the map we just defined.

## Algebra of $\mathcal{L}(V, W)$

## Def'n:

Let $S, T \in \mathcal{L}(V, W)$ and $\lambda \in \mathbb{F}$. We define for all $v \in V$

$$
(S+T)(v)=S v+T v
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and

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## Prop'n:

With the addition and scalar multiplication defined above, $\mathcal{L}(V, W)$ is a vector space.

## More algebra of $\mathcal{L}(V, W)$

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Let $U, V, W$ be vector spaces. If $T \in \mathcal{L}(U, V), S \in \mathcal{L}(V, W)$, then we define $S T \in \mathcal{L}(U, W)$ for $u \in U$ as

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\begin{gathered}
T D(p(x))=T\left(p^{\prime}(x)\right)=x^{2} p^{\prime}(x) \\
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Notice that $T D \neq D T$.

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for $T \in \mathcal{L}(V, W)$

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■ identity:

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for $T \in \mathcal{L}(V, W)$
■ distributive properties:

$$
\begin{aligned}
& \left(S_{1}+S_{2}\right) T=S_{1} T+S_{2} T \\
& S\left(T_{1}+T_{2}\right)=S T_{1}+S T_{2}
\end{aligned}
$$

where $T^{\prime} s \in \mathcal{L}(U, V)$ and $S^{\prime} s \in \mathcal{L}(V, W)$

## Break



## Discussion Questions

1. Prove that all linear maps send 0 to 0 .
2. Describe the subspaces of $\mathbb{R}^{3}$ and their dimensions.
3. Let $U=\left\{p \in \mathcal{P}_{4}(\mathbb{R}): p^{\prime \prime}(6)=0\right\}$.
(a) Find a basis of $U$.
(b) Extend your basis to one of $\mathcal{P}_{4}(\mathbb{R})$.
(c) Find a subspace $W$ such that $\mathcal{P}_{4}(\mathbb{F})=U \oplus W$.
4. Suppose $b, c \in \mathbb{R}$. Define $T: \mathbb{R}^{3} \rightarrow \mathbb{R}^{2}$ by
$T(x, y, z)=(2 x-4 y+3 z+b, 6 x+c x y z)$. Show that $T$ is linear if and only if $b=c=0$.
5. Construct a linear map $T: \mathbb{R}^{3} \rightarrow \mathbb{R}^{2}$ such that $T(3,0,2)=(3,4)$ and $T(1,1,1)=(1,1)$. Or show why this is impossible. what about one such that $T(3,0,2)=(3,4)$ and $T(6,0,4)=(1,1)$ ?

## Discussion Question Hints/Solutions

1. $T(0)=T(0+0)=T(0)+T(0)$. Adding the additive inverse of $T(0)$ to each side gives $0=T(0)$.
2. | $\operatorname{dim}$ | $U \subseteq \mathbb{R}^{3}$ |
| :---: | :---: |
| 0 | $\{0\}$ |
| 1 | all lines in $\mathbb{R}^{3}$ through the origin |
| 2 | all planes in $\mathbb{R}^{3}$ through the origin |
| 3 | $\mathbb{R}^{3}$ |
3. (a) Show that the following are linearly ind. and span:
$1,(x-6),(x-6)^{3},(x-6)^{4}$
(b) The polynomial $(x-6)^{2}$ is not in $U$ and this list is lin ind of the right length.
(c) Let $W=\operatorname{span}\left((x-6)^{2}\right)$.

## Discussion Question Hints/Solutions

4. First, if $b=c=0$. We can show that $T$ is additive and satisfies homogeneity.
Next, notice that
$\lambda T(x, y, z) \neq T(\lambda x, \lambda y, \lambda z)=\left(2 \lambda x-4 \lambda y+3 \lambda z+b, 6 \lambda x+c \lambda^{3} x y z\right)$ for any $\lambda \in \mathbb{R}$.
5. We can use the basis of domain prop'n to define a map in the first case. One example is to say $T(3,0,2)=(3,4)$, $T(1,1,1)=(1,1)$, and $T(0,1,0)=(2,1)$ (we needed to choose a third vector and output to have a basis of the domain $\mathbb{R}^{3}$ ). The second will not be linear because $(3,0,2)=\frac{1}{2}(6,0,4)$ but $T(3,0,2) \neq \frac{1}{2} T(6,0,4)$.

## References

[Axl14] Sheldon Axter. Linear Algebra Done Right. Undergraduate Texts in Mathematics. Springer Cham, 2014.

