



Lecture 9: Isomorphisms

MATH 110-3

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Invertible

Def'n:

A linear map $T \in \mathcal{L}(V, W)$ is called **invertible** if there exists a map $S \in \mathcal{L}(W, V)$ such that ST is the identity on V and TS is the identity on W .

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Notation

Write the inverse of T as T^{-1} .

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S'pose $ST = I$. We have that S, T are both invertible. So $S(TT^{-1}) = I(T^{-1}) = T^{-1}$. And $TS = (TT^{-1})S = I$.

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Let $T^{-1}w := v$ so that $T(T^{-1}w) = Tv = w$.

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To complete the proof... show T^{-1} is linear.

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- Multiplication by x^2 from $\mathcal{P}(\mathbb{R})$ to itself.
- Backwards shift map $\mathbb{F}^\infty \rightarrow \mathbb{F}^\infty$.
- $T(x, y) = (0, y)$

Isomorphisms

Def'n:

An invertible linear map is also called an **isomorphism**.

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Two vector spaces are called **isomorphic** if there exists an isomorphism between them.

Dimension and Isomorphisms

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Proof. Suppose V, W are isomorphic \mathbb{F} -vector spaces. Then there is an isomorphism between them: T .

T is injective, so $\text{null } T = 0$. T is surjective, so $\text{range } T = W$. Thus, by the formula

$$\dim V = \dim \text{null } T + \dim \text{range } T,$$

we have

$$\dim V = 0 + \dim W.$$

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The map

$$T(c_1v_1 + \dots + c_nv_n) = c_1w_1 + \dots + c_nw_n$$

is an isomorphism. \square

Maps and Matrices

Prop'n:

Suppose v_1, \dots, v_m is a basis of V and w_1, \dots, w_n is a basis of W . Then \mathcal{M} is an isomorphism between $\mathcal{L}(V, W)$ and $\mathbb{F}^{n,m}$.

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Proof...

- \mathcal{M} is linear
- \mathcal{M} is injective
- \mathcal{M} is surjective

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Remarkable result...

Prop'n:

Suppose V is *finite-dimensional* and $T \in \mathcal{L}(V)$. Then the following are equivalent:

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Break



Discussion Questions

1. Suppose $T \in \mathcal{L}(U, V)$ and $S \in \mathcal{L}(V, W)$ are both invertible linear maps. Prove that $ST \in \mathcal{L}(U, W)$ is invertible and that its inverse is $(ST)^{-1} = T^{-1}S^{-1}$.
2. Come up with an example of a linear map that is injective but not surjective and one that is surjective but not injective.
3. Suppose $D \in \mathcal{L}(\mathcal{P}_3(\mathbb{R}), \mathcal{P}_2(\mathbb{R}))$ is the differentiation map defined $Dp = p'$. Find a basis of $\mathcal{P}_3(\mathbb{R})$ and a basis of $\mathcal{P}_2(\mathbb{R})$ such that the matrix of D with respect to these bases is

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}.$$

Discussion Questions

- Suppose V and W are finite-dimensional and $T \in \mathcal{L}(V, W)$. Prove there exists a basis of V and a basis of W such that with respect to these bases, all entries of $\mathcal{M}(T)$ are 0 except the entries in row j , column j equal 1 for all j such that $1 \leq j \leq \dim \text{range } T$.
- Find two 2×2 matrices that do not commute.
- Let a_0, \dots, a_n be any scalars in \mathbb{F} . Consider the basis $1, x, \dots, x^n$ of $\mathcal{P}(\mathbb{F})$ and the standard basis of \mathbb{F}^{n+1} . Write the matrix of the transformation

$$T : \mathcal{P}_n(\mathbb{F}) \rightarrow \mathbb{F}^{n+1}$$

$$p \rightarrow (p(a_0), p(a_1), \dots, p(a_n))$$

with respect to these bases.

Discussion Questions

7. Suppose V is finite dimensional and $S, T, U \in \mathcal{L}(V)$ and $STU = I$. Show that T is invertible and that $T^{-1} = US$.
8. Suppose V is finite dimensional and $R, S, T \in \mathcal{L}(V)$ are such that RST is surjective. Prove S is injective.

Discussion Question Hints/Solutions

1.

$$(ST)(T^{-1}S^{-1}) = S(TT^{-1})S^{-1} = SIS^{-1} = SS^{-1} = I$$

$$(T^{-1}S^{-1})(ST) = T^{-1}(S^{-1}S)T = T^{-1}IT = T^{-1}T = I$$

2. One solution is example 3.68 in [Axl14].

3. Basis for $\mathcal{P}_3(\mathbb{R})$: $x^3, x^2, x, 1$

Basis for $\mathcal{P}_2(\mathbb{R})$: $3x^2, 2x, 1$

5. An example of two matrices that do not commute are

$$\begin{pmatrix} 2 & 4 \\ 3 & 5 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix}$$

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- Pick u_1, \dots, u_k to be a basis for $\text{null } T$. Extend to a basis $u_1, \dots, u_k, v_1, \dots, v_n$ of V . As in the proof of Rank-Nullity, Tv_1, \dots, Tv_n span $\text{range } T$. Extend this list to a basis $Tv_1, \dots, Tv_n, w_1, \dots, w_m$ of W .

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4. Pick u_1, \dots, u_k to be a basis for null T . Extend to a basis $u_1, \dots, u_k, v_1, \dots, v_n$ of V . As in the proof of Rank-Nullity, Tv_1, \dots, Tv_n span range T . Extend this list to a basis $Tv_1, \dots, Tv_n, w_1, \dots, w_m$ of W . These are the desired bases as...

$$Tv_1 = 1 \cdot Tv_1 + 0 \cdot T_2 + 0 \cdot w_1 + \dots + 0 \cdot w_m$$

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$$Tv_n = 0 \cdot Tv_1 + \dots + 1 \cdot T_n + 0 \cdot w_1 + \dots + 0 \cdot w_m$$

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$$Tv_n = 0 \cdot Tv_1 + \dots + 1 \cdot T_n + 0 \cdot w_1 + \dots + 0 \cdot w_m$$

...giving the desired matrix form.

Discussion Question Hints/Solutions

6. This is the **Vandermonde matrix**.
7. Using prop'n from lecture, $(ST)U = I$ implies $U(ST) = I$. This implies $US = T^{-1}$.
8. RST surjective implies $R(ST)$ invertible. $R(ST)$ invertible implies ST invertible. ST invertible implies S is invertible which implies S is surjective.

References

- [Axl14] Sheldon Axler.
Linear Algebra Done Right.
Undergraduate Texts in Mathematics. Springer Cham, 2014.